Parts 1 and 2 are independent.

Part 1 – Identification of standalone joints

Below are three different joints taken from some larger mechanism. Their respective groups of parts are colored in blue and red (you should **colour yourself the third one**). Fill-in the name of these joints with a correctly oriented symbol.

Local drawing of the joint	Name a joint and place a <u>correctly oriented</u> symbol
Colour-in the drawing below using a different colour for each group of parts	

Part 2 – Scotch Yoke

A scotch yoke mechanism transforms a revolute motion into reciprocating translation. Here, it is used to drive a double action pump.

It is composed of three groups of parts colored on page 3:

WHITE - BASE

BLUE – SHAFT

RED – PISTON

Q4. Complete the bubble diagram of joints below (name and orientation)



Q5. On Page 3, mark the <u>extreme left position</u> of the point P (in cross-section A-A) during operation.

Q6. Complete below the kinematic diagram of the system by using correct symbols.





