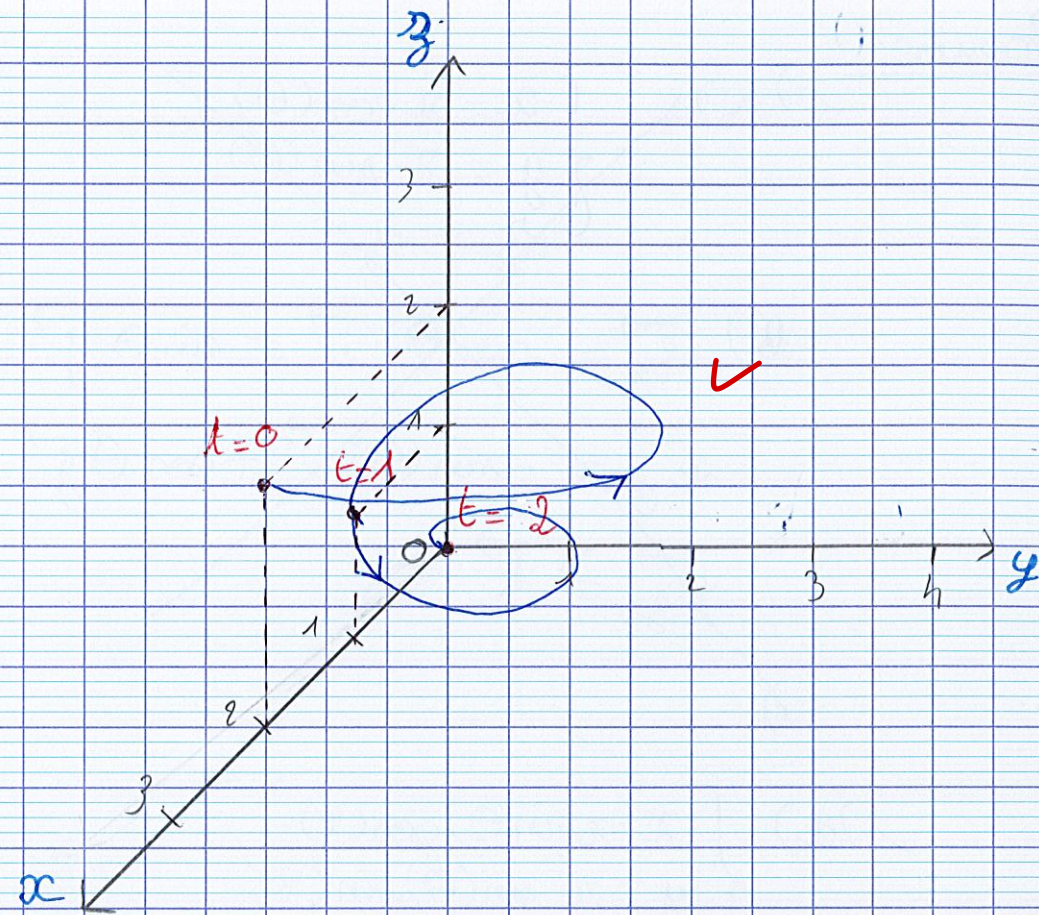


1,25 b)



0,5 c) $\vec{e}_\rho(t) = \sin(\theta) \cos(\varphi) \vec{i} + \sin(\theta) \sin(\varphi) \vec{j} + \cos(\theta) \vec{k}$
 $= \sin\left(\frac{\pi}{4}\right) \cos(2\pi t) \vec{i} + \sin\left(\frac{\pi}{4}\right) \sin(2\pi t) \vec{j} + \cos\left(\frac{\pi}{4}\right) \vec{k}$
 $= \frac{\sqrt{2} \cos(2\pi t)}{2} \vec{i} + \frac{\sqrt{2} \sin(2\pi t)}{2} \vec{j} + \frac{\sqrt{2}}{2} \vec{k}$ ✓

1 d) $\frac{d\vec{e}_\rho}{dt} = \frac{-\sqrt{2} \times 2\pi \sin(2\pi t)}{2} \vec{i} + \frac{\sqrt{2} \times 2\pi \cos(2\pi t)}{2} \vec{j}$
 $= -\sqrt{2} \pi \sin(2\pi t) \vec{i} + \sqrt{2} \pi \cos(2\pi t) \vec{j}$
 $= \sqrt{2} \pi (-\sin(2\pi t) \vec{i} + \cos(2\pi t) \vec{j})$
 $= \sqrt{2} \pi (-\sin(\varphi(t)) \vec{i} + \cos(\varphi(t)) \vec{j})$
 $= \sqrt{2} \pi \vec{e}_\varphi$ ✓

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Exercise 2)

Define $\omega = df$
 $\omega = \frac{yz + xy + 1}{z+x} dx + x dy + \frac{1}{x+z} dz$

2 1) $\frac{d^2 f}{dx dy} = 1$ ✓ $\frac{d^2 f}{dy dx} = \frac{x+z}{x+z} = 1$ ✓

$\frac{d^2 f}{dz dy} = 0$ ✓ $\frac{d^2 f}{dy dz} = 0$ ✓

$\frac{d^2 f}{dx dz} = \frac{-1}{(x+z)^2}$ ✓ $\frac{d^2 f}{dz dx} = \frac{y(z+x) + 1 \times (yz + xy + 1)}{(x+z)^2}$
 $= \frac{xy + zy - zy - xy - 1}{(x+z)^2} = \frac{-1}{(x+z)^2}$ ✓

Thus, we have: $\frac{d^2 f}{dx dy} = \frac{d^2 f}{dy dx}$
 $\frac{d^2 f}{dz dy} = \frac{d^2 f}{dy dz}$
 $\frac{d^2 f}{dx dz} = \frac{d^2 f}{dz dx}$

Thus, ω is a closed form. ✓

1,5

2) condition?

Integrate df by y:

$$f = xy + g(x) + h(z)$$

Differentiate by z:

$$\frac{df}{dz} = 0 + 0 + h'(z), \text{ hence } h'(z) = \frac{1}{x+z}$$
$$\text{hence } h(z) = \ln(x+z)$$

Integrate by z:

$$f = xy + \ln(x+z) + h(z)$$

Differentiate by x:

$$\frac{df}{dx} = y + \frac{1}{x+z} + h'(z) = \frac{yx + yz + 1}{x+z} + h'(z)$$
$$\text{hence } h'(z) = 0$$
$$\text{hence } h(z) = C, C \in \mathbb{R}$$

$$\text{Hence } f(x, y, z) = xy + \ln(x+z) + C \checkmark$$

→ this is a consequence!

Thus there exists a function f defined on D such that df = ω, hence we can conclude ω is an exact form. ✗

Exercise 4)

1) a)
$$\begin{cases} x = r \cos(\theta) \\ y = r \sin(\theta) \\ z = z \end{cases}$$

b)
$$\vec{e}_r = \cos(\theta) \vec{i} + \sin(\theta) \vec{j}$$

$$\vec{e}_\theta = -\sin(\theta) \vec{i} + \cos(\theta) \vec{j}$$

$$\vec{e}_z = \vec{k}$$

1,5

1) a)
$$\begin{cases} x = r \sin(\theta) \cos(\varphi) \checkmark \\ y = r \sin(\theta) \sin(\varphi) \checkmark \\ z = r \cos(\theta) \checkmark \end{cases}$$

1,5

b)
$$\vec{e}_r = \sin(\theta) \cos(\varphi) \vec{i} + \sin(\theta) \sin(\varphi) \vec{j} + \cos(\theta) \vec{k} \checkmark$$

$$\vec{e}_\theta = \cos(\theta) \cos(\varphi) \vec{i} + \cos(\theta) \sin(\varphi) \vec{j} - \sin(\theta) \vec{k} \checkmark$$

$$\vec{e}_\varphi = -\sin(\varphi) \vec{i} + \cos(\varphi) \vec{j} \checkmark$$

0,5

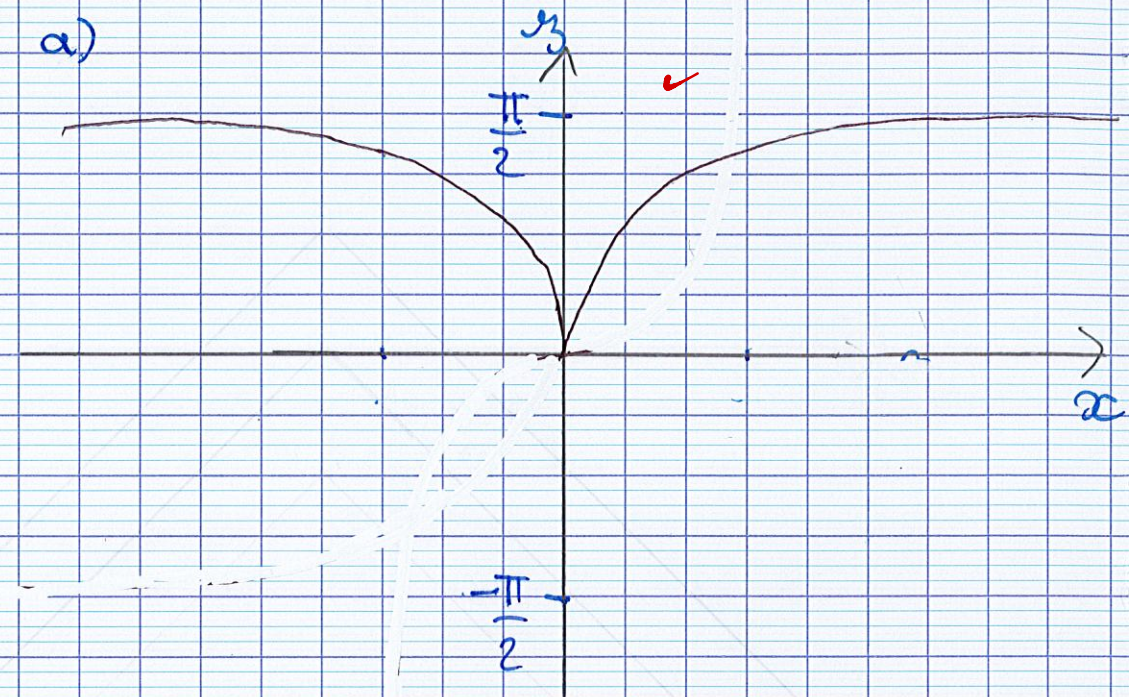
c)
$$\vec{OM} = r \vec{e}_r \checkmark$$

2)
$$\begin{cases} r(t) = (2-t)\sqrt{2} \\ \theta(t) = \frac{\pi}{4} \\ \varphi(t) = 2\pi t \end{cases} \quad t \in [0, 2]$$

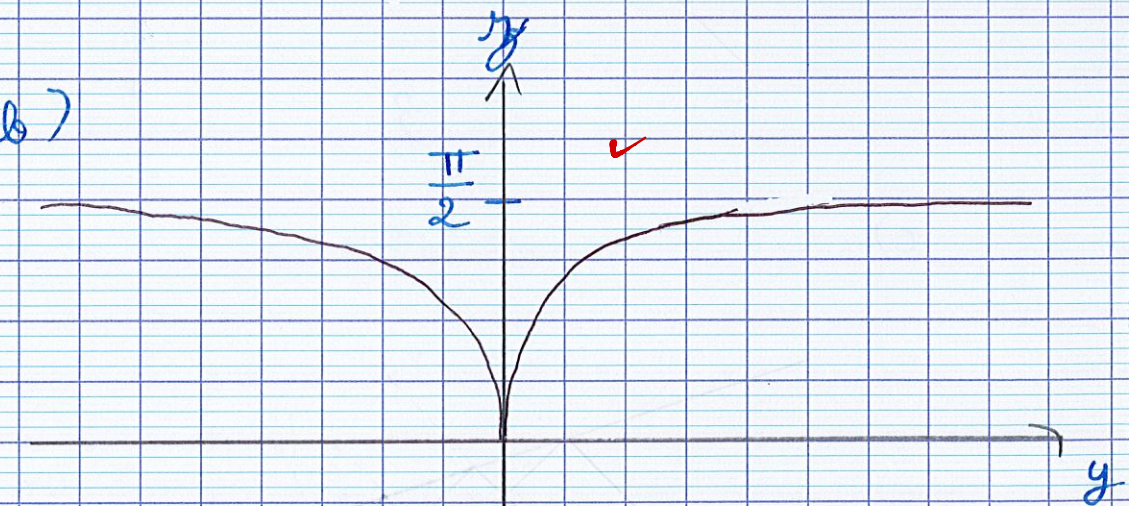
0,5

a) Since θ is constant, this trajectory is on a cone. missing more details on the cone shape!

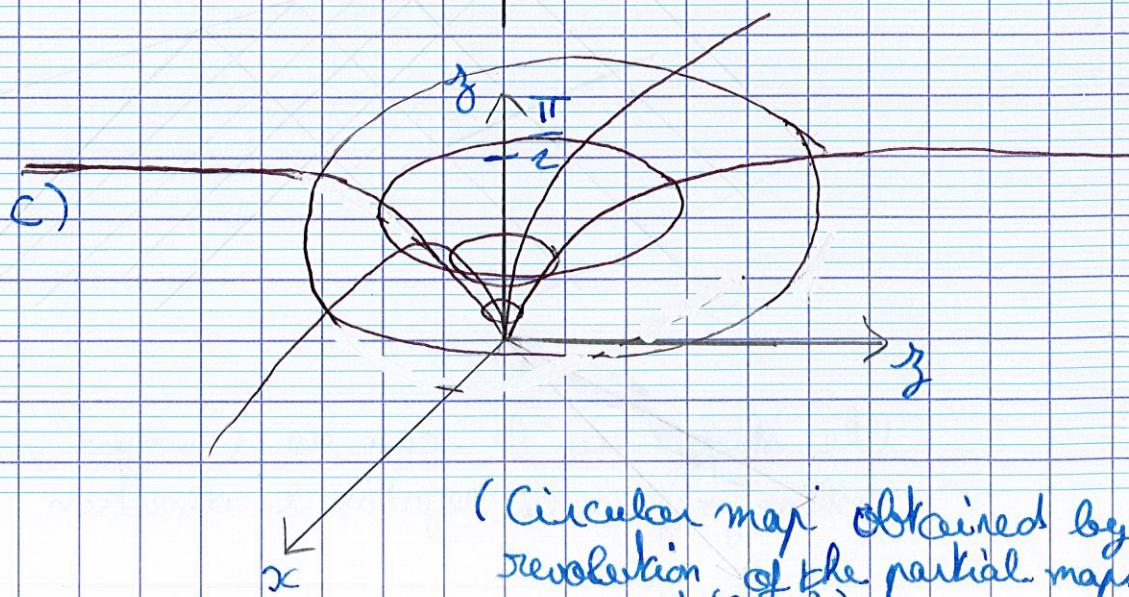
2) a) 0,5



0,25 b)



1) c)



(Circular map obtained by revolution of the partial maps)

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① e) $\vec{r}(t) = \vec{OM}'(t) = \frac{d\vec{OM}}{dt} = \frac{d(\lambda \vec{e}_r)}{dt}$
 $= \frac{d\lambda}{dt} \vec{e}_r(t) + \lambda \frac{d\vec{e}_r}{dt}$ ✓
 $= -\sqrt{2} \vec{e}_r(t) + \sqrt{2} \pi \vec{e}_\varphi(t) (2-t)\sqrt{2}$
 $= -\sqrt{2} \vec{e}_r(t) + 2\pi(2-t) \vec{e}_\varphi(t)$ ✓
 (with \vec{e}_r and \vec{e}_φ defined previously)

Exercise 3)

$$C = k \begin{pmatrix} 1 & -1 \\ R_1 & R_2 \end{pmatrix}^{-1} = \frac{k R_1 R_2}{R_2 - R_1}$$
 ✓

③ 1) $\delta C = \frac{R_1 R_2}{R_2 - R_1} \delta k + \frac{k R_2 (R_2 - R_1) - k R_1 R_2 \times -1}{(R_2 - R_1)^2}$
 $+ \frac{k R_1 (R_2 - R_1) - k R_1 R_2 \times 1}{(R_2 - R_1)^2} \delta R_2$

$$\delta C = \frac{R_1 R_2}{R_2 - R_1} \delta k + \frac{k R_2^2}{(R_2 - R_1)^2} \delta R_1 - \frac{k R_1^2}{(R_2 - R_1)^2} \delta R_2$$
 ✓

Hence (NA):

$$\delta C = \frac{1 \times 2 \times 10^{-3}}{2-1} + \frac{1 \times 2^2}{(2-1)^2} \delta R_1 - \frac{1 \times 1^2 \times 4}{(2-1)^2} \delta R_2$$

$$\delta C = 0,002 + 4\delta R_1 - 4\delta R_1 = 0,002 \quad \checkmark \quad \text{units?} \quad (0,75) \quad b)$$

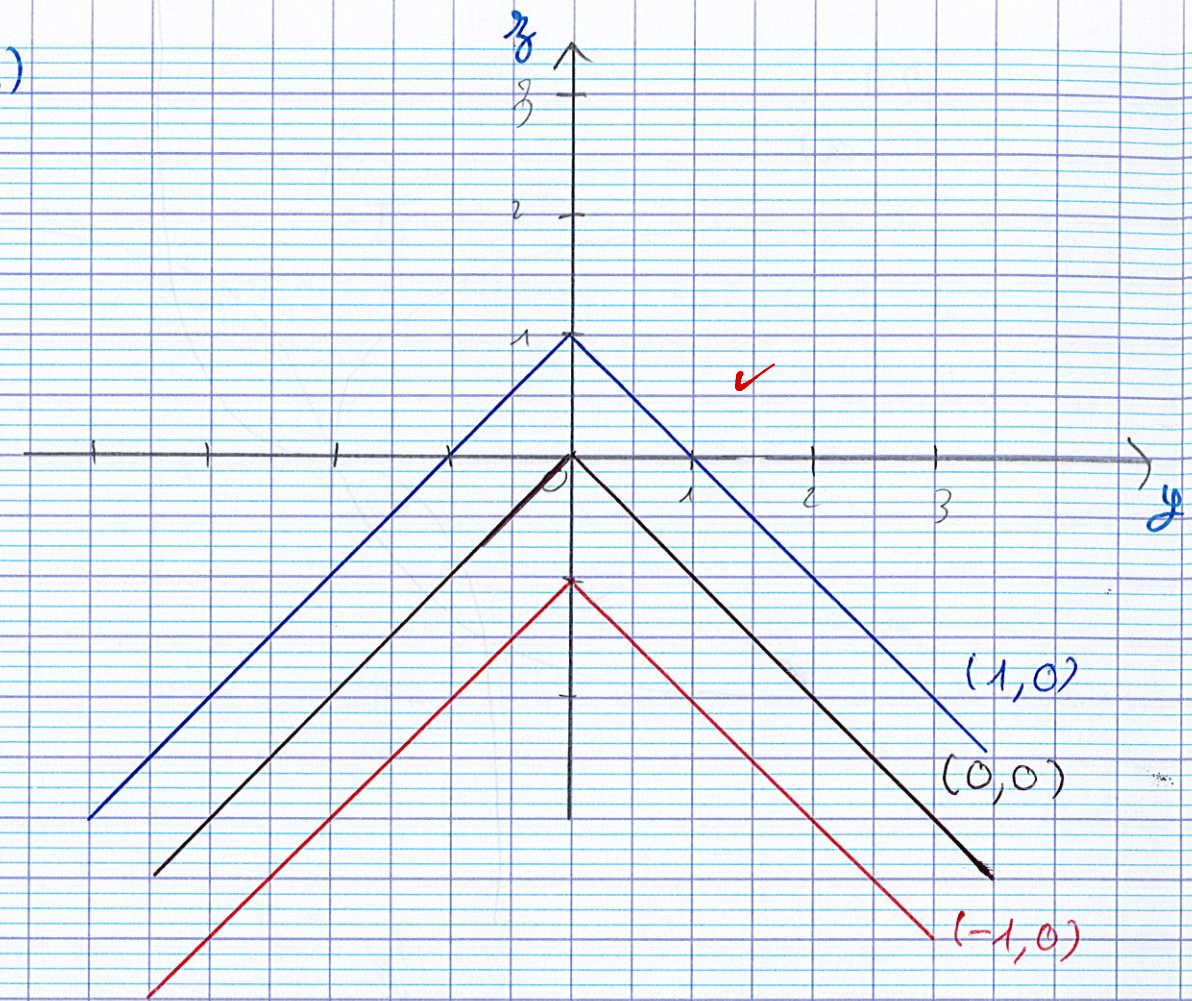
$$2) \Delta C = \left| \frac{R_1 R_2}{R_2 - R_1} \right| \Delta R + \left| \frac{k R_2^2}{(R_2 - R_1)^2} \right| \Delta R_1 + \left| \frac{k R_1^2}{(R_2 - R_1)^2} \right| \Delta R_2 \quad \checkmark$$

Thus, (N.A.), we have:

$$\Delta C = \left| \frac{1 \times 2}{2-1} \right| 10^{-3} + \left| \frac{1 \times 2^2}{(2-1)^2} \right| 10^{-3} + \left| \frac{1 \times 1^2}{(2-1)^2} \right| 10^{-3}$$

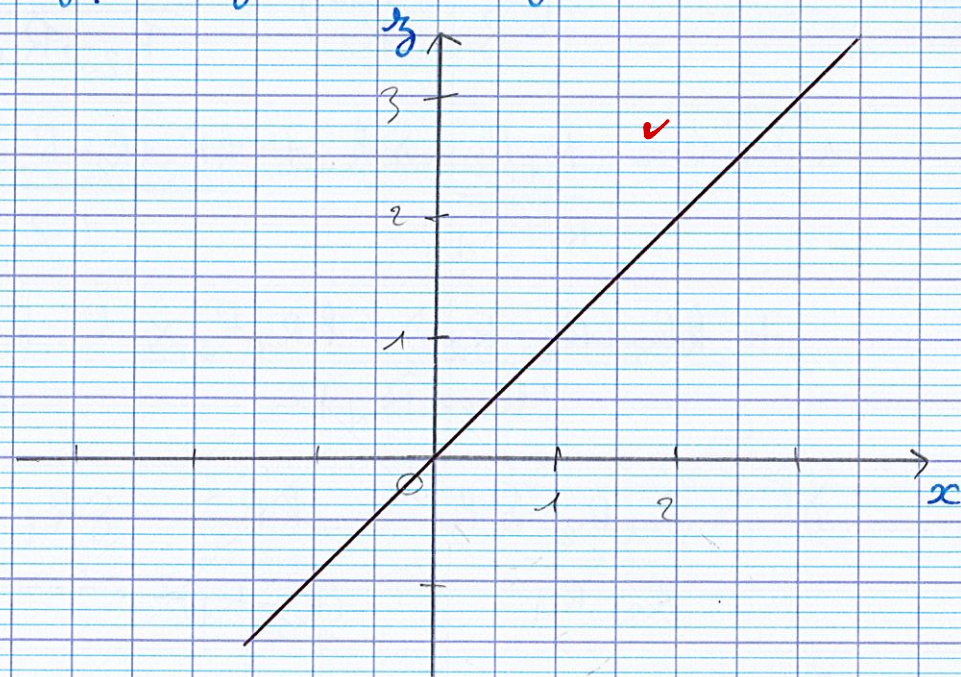
$$\Delta C = 2 \times 10^{-3} + 4 \times 10^{-3} + 1 \times 10^{-3}$$

$$\Delta C = 0,007 \quad \checkmark \quad \text{units?}$$

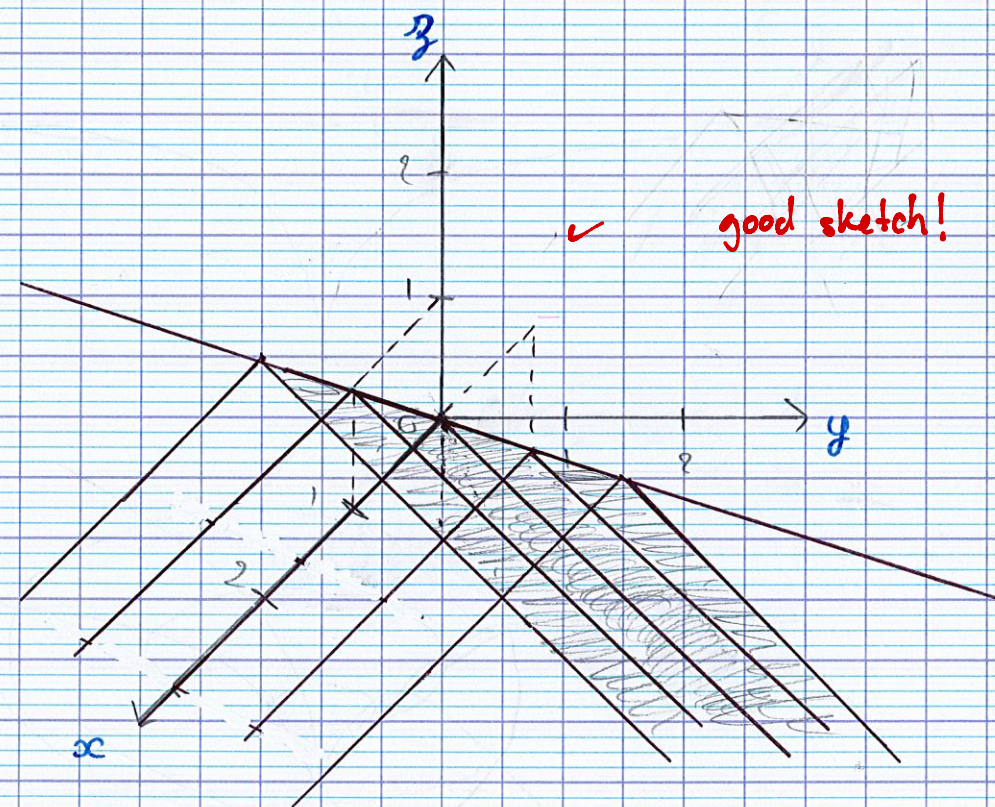


Exercise 1) 1) $f: (x, y) \mapsto x - |y|$

(0,75) a)



(1) c)



The shape can be seen as a "roof", descending when going in the negative x direction. \checkmark