

Instructions: items in **red** are graded, items in black are for information only

EX1	3 pts
<p><b>1.1</b></p> $dC = \vec{B} \cdot d\vec{OM} = Pdx + Qdy + Rdz$ $\frac{\partial P}{\partial z} = \frac{\partial R}{\partial x} = 0, \quad \frac{\partial P}{\partial z} = \frac{\partial R}{\partial x} = 0 \quad \text{and} \quad \frac{\partial P}{\partial z} = \frac{\partial R}{\partial x} = 0$ <p><math>dC</math> is hence <b>closed</b> and since <math>P, Q</math> and <math>R</math> are of class at least <math>C^1</math> on <math>\mathbb{R}^3</math> then it is also <b>exact</b>, then <math>\vec{B}</math> is derived from a potential</p>	<p><b>Total: 1 pt</b></p> <p>0,25 + 0,25 + 0,25</p> <p>0,25</p>
<p><b>1.2</b></p> <p><math>\vec{B} = -\nabla V</math>, accepted if <math>\vec{B} = \nabla V</math> with the different answers that go with it</p> $-\frac{\partial V}{\partial x} = y^2 \cos(x) \Leftrightarrow v(x, y, z) = -y^2 \sin(x) + f(y, z)$ $-\frac{\partial V}{\partial y} = -\frac{\partial}{\partial y} (-y^2 \sin(x) + f(y, z)) = 2y \sin(x) + e^{2z} \Leftrightarrow f(y, z) = -ye^{2z} + g(z)$ <p><math>v(x, y, z) = -y^2 \sin(x) - ye^{2z} + 1</math> or <math>v(x, y, z) = y^2 \sin(x) + ye^{2z} + 1</math> (if <math>\vec{B} = \nabla V</math>)</p>	<p><b>Total: 1,5pt</b></p> <p>0,5</p> <p>0,5</p> <p>0,5</p>
<p><b>1.3</b></p> $C = \int_x^y \vec{B} \cdot \vec{dl} = V(x) - V(y)$ <p><math>V(x) - V(y) = 0 - (-11) = 11</math> or <math>-11</math> (if <math>\vec{B} = \nabla V</math>)</p>	<p><b>Total: 0,5pt</b></p> <p>0,25</p> <p>0,25</p>
EX2	4 pts + 0,5 (bonus)
<p><b>2.1</b></p> $\vec{F}(x, y) \times d\vec{OM} = \vec{0}$ $\frac{x}{2} dy - y dx = 0 \quad \text{and no variation in } z$ $y = k'x^2$ <p>Parabolas in the <math>xOy</math> plane and oriented from the origin outwards (bonus)</p>	<p><b>Total: 1 pt</b></p> <p>0,5</p> <p>0,5</p> <p>0,5 + 0,5 (bonus)</p>

<p><b>2.2</b></p> $dC = \left[ \frac{x}{2} \vec{e}_x + y \vec{e}_y \right] \cdot \left[ dx \vec{e}_x + dy \vec{e}_y \right]$ <p>Closed, since <math>\frac{\partial y}{\partial x} = 0 = \frac{\partial \frac{x}{2}}{\partial y}</math></p> <p><math>\frac{x}{2}</math> and <math>y</math> are <math>C^1</math> on <math>\mathbb{R}^2 \Rightarrow</math> exact, hence <math>\vec{F}</math> derives from a potential</p> <p>For the potential <math>\frac{x}{2} \vec{e}_x + y \vec{e}_y = -\nabla \phi</math></p> <p>Which gives <math>\Rightarrow \phi(x, y) = -\frac{x^2}{4} + f(y)</math></p> <p>The potential is <math>\phi(x, y) = -\frac{x^2}{4} - \frac{y^2}{2} + k</math></p>	<p><b>Total: 1pt</b></p> <p>0,25</p> <p>0,25</p> <p>0,25</p>
<p><b>2.3</b></p> <p><math>\phi(x, y) = C</math> with <math>C</math> a constant</p> <p><math>\frac{x^2}{4} + \frac{y^2}{4} = C'</math> which is the equation of ellipses centered at the origin</p> <p>appropriate sketch</p>	<p><b>Total: 0,5pt</b></p> <p>0,5 + 0,5</p> <p>0,5</p>
<p><b>EX3</b></p>	<p><b>6 pts + 0,5 (bonus)</b></p>
<p><b>3.1</b></p> $\phi_{AOC} = \iint_{AOC} \vec{F} \cdot \vec{dS} \quad \text{with } y = 0 \text{ and } \vec{dS} = (-\vec{e}_y) dx dz$ <p><math>\phi_{AOC} = 0</math>, and similarly <math>\phi_{COB} = 0</math> and <math>\phi_{AOB} = 0</math></p> <p>They are the same since <math>\vec{F}</math> is always normal to <math>\vec{dS}</math></p>	<p><b>Total: 1 pt</b></p> <p>0,25 + 0,25 + 0,25</p> <p>0,25</p>

<p><b>3.2</b></p> <p>One possible parametrisation is by using the vectors <math>\overrightarrow{CA}</math> and <math>\overrightarrow{CB}</math>:</p> $\overrightarrow{OM} = u\overrightarrow{CA} + v\overrightarrow{CB} + 2\overrightarrow{e}_z$ $\overrightarrow{OM} = u(\overrightarrow{e}_x - 2\overrightarrow{e}_z) + v(\overrightarrow{e}_y - 2\overrightarrow{e}_z) + 2\overrightarrow{e}_z = u\overrightarrow{e}_x + v\overrightarrow{e}_y + 2(-u - v + 1)\overrightarrow{e}_z,$ $u, v \in [0,1]$ <p>Let <math>\vec{p} = \frac{\partial \overrightarrow{OM}}{\partial u} \times \frac{\partial \overrightarrow{OM}}{\partial v}</math> be a vector normal to <math>ABC</math></p> $\frac{\partial}{\partial u} [u\overrightarrow{e}_x + v\overrightarrow{e}_y + 2(-u - v + 1)\overrightarrow{e}_z] = \overrightarrow{e}_x - 2\overrightarrow{e}_z$ $\frac{\partial}{\partial v} [u\overrightarrow{e}_x + v\overrightarrow{e}_y + 2(-u - v + 1)\overrightarrow{e}_z] = \overrightarrow{e}_y - 2\overrightarrow{e}_z$ <p>And hence, <math>\vec{p} = 2\overrightarrow{e}_x + 2\overrightarrow{e}_y + \overrightarrow{e}_z</math></p> <p>Finally <math>\vec{n} = \frac{\vec{p}}{\ \vec{p}\ } = \frac{1}{3} [2\overrightarrow{e}_x + 2\overrightarrow{e}_y + \overrightarrow{e}_z]</math>, <span style="float: right;">cqfd</span></p>	<p><b>Total: 2,75pt</b></p> <p>1</p> <p>0,5</p> <p>0,25</p> <p>0,25</p> <p>0,5</p> <p>0,25</p>
<p><b>3.3</b></p> <p>We already have a parametrisation as seen in 3.2. We need to demonstrate that it is equivalent to the one given.</p> <p>If we take <math>u = ab</math> and <math>-u - v = -a</math> then we have that <math>v = a(1 - b)</math> we can rewrite the parametrisation of 3.2 replacing <math>u</math> and <math>v</math> and get</p> $\overrightarrow{OM} = ab\overrightarrow{e}_x + a(1 - b)\overrightarrow{e}_y + 2(1 - a)\overrightarrow{e}_z \quad \text{with. } a, b \in [0,1]$	<p><b>Total: 0,5pt (bonus)</b></p> <p>0,5 (bonus)</p>
<p><b>3.4</b></p> $\phi_{ABC} = \iint_{ABC} \vec{F}_{uv} \cdot \vec{dS}_{uv} \text{ with } \vec{dS} = \frac{1}{3} [2\overrightarrow{e}_x + 2\overrightarrow{e}_y + \overrightarrow{e}_z] \, dudv \text{ and } u, v \in [0,1]$ $= \int_{u=0}^1 \int_{v=0}^1 \left\{ u\overrightarrow{e}_x + v\overrightarrow{e}_y + \frac{1}{2} [2(-u - v + 1)]\overrightarrow{e}_z \right\} \cdot \left\{ \frac{2}{3}\overrightarrow{e}_x + \frac{2}{3}\overrightarrow{e}_y + \frac{1}{3}\overrightarrow{e}_z \right\} \, dudv$ $= \int_0^1 \left[ \frac{1}{3}uv + \frac{v^2}{6} + \frac{1}{3}v \right]_0^1 du$ $= \frac{1}{2}$	<p><b>Total: 1pt</b></p> <p>0,25</p> <p>0,25</p> <p>0,25</p> <p>0,25</p>

<p><b>3.5</b></p> $C_{AO} = \int_{AO} \vec{F} \cdot d\vec{OM} \quad \text{with } AO : y = 0, z = 0, x \in [0,1] \text{ and } d\vec{OM} = dx \vec{e}_x$ $C_{AO} = \frac{1}{2}$ $C_{OB} = \int_{OB} \vec{F} \cdot d\vec{OM} \quad \text{with } OB : y \in [0,1], z = 0, x = 0 \text{ and } d\vec{OM} = dy \vec{e}_y$ $C_{AO} = -\frac{1}{2}$ <p>Not the same due to the symmetry of <math>\vec{F}</math> on <math>x</math> and <math>y \Rightarrow C_{AO} = C_{BO}</math> and hence  <math>\Rightarrow C_{AO} = -C_{OB}</math></p>	<p><b>Total: 0,75pt</b></p> <p>0,25</p> <p>0,25</p> <p>0,25</p>
<p><b>3.6</b></p> <p><math>\vec{F}</math> is conservative since it is derived from a potential</p> $\frac{\partial}{\partial x} \left( \frac{z}{2} \right) = 0 = \frac{\partial}{\partial z} (x), \quad \frac{\partial}{\partial x} (y) = 0 = \frac{\partial}{\partial y} (x) \quad \text{and} \quad \frac{\partial}{\partial y} \left( \frac{z}{2} \right) = 0 = \frac{\partial}{\partial z} (y), \text{ hence closed}$ <p><math>\vec{F}</math> is <math>C^1</math> on <math>\mathbb{R}^3 \Rightarrow</math> exact, hence <math>\vec{F}</math> derives from a potential <math>\Rightarrow C = 0</math> on a closed path</p>	<p><b>Total: 0,5pt</b></p> <p>0,25</p> <p>0,25</p>
<p><b>EX4</b></p>	<p><b>4 pts</b></p>
<p><b>4.1</b></p> $\phi_{D_H} = \iint_{D_H} \vec{E}_1 \cdot \vec{dS} \quad \text{with } \vec{dS} = r d\theta dr \vec{e}_z$ <p>Since <math>\vec{E}_1</math> is according to <math>\vec{e}_r</math>, then <math>\vec{E}_1 \cdot \vec{dS} = 0</math> and hence <math>\phi_{D_H} = 0</math></p> $\phi_{D_{-H}} = \iint_{D_{-H}} \vec{E}_1 \cdot \vec{dS} \quad \text{with } \vec{dS} = r d\theta dr (-\vec{e}_z)$ <p>same thing for <math>\phi_{D_{-H}} = 0</math></p>	<p><b>Total: 1 pt</b></p> <p>0,25</p> <p>0,25</p>
<p><b>4.2</b></p> $\phi_C = \iint_C \vec{E}_1 \cdot \vec{dS} \quad \text{with } \vec{dS} = r d\theta dz \vec{e}_r \quad \text{and } r = a$ $\phi_C = 4\pi a H E(a)$	<p><b>Total: 1pt</b></p> <p>0,5</p> <p>0,5</p>
<p><b>4.3</b></p> <p><math>\phi_A = \phi_{D_H} + \phi_{D_{-H}} + \phi_C</math> and given the prior results we have</p> $\phi_A = 0 + 0 + 4\pi a H \frac{4a}{1+a^2} = \frac{16\pi H a^2}{1+a^2}$ <p>A.N. <math>\phi_A = \frac{64\pi}{5}</math></p>	<p><b>Total: 0,5pt</b></p> <p>0,5</p> <p>0,5</p>

<b>4.4</b>	<b>Total: 1,5pt</b>
$C_{AB} = \int_B^A \vec{E} \cdot d\vec{OM} \text{ with } d\vec{OM} = dr\vec{e}_r + r d\theta\vec{e}_\theta + dz\vec{e}_z$	0,5
<p>With the variable change <math>u = 1 + r^2</math>; <math>du = 2r dr</math> we have</p> $C_{AB} = 2 \int_1^5 \frac{1}{u} du = 2 [\ln(u)]_1^5$	0,5
$C_{AB} = 2 \ln(5)$	0,5

<b>EX5</b>	<b>3 pts</b>
$C_{ABCOA} = C_{AB} + C_{BO} + C_{OC} + C_{CA}$	
$C_{AB} = \int_{AB} \vec{F} \cdot d\vec{OM} \text{ with } r = 1, \phi = 0, \theta = \pi/2 \rightarrow 0 \text{ and } d\vec{OM} = r d\theta\vec{e}_\theta = d\theta\vec{e}_\theta$	0,5
$C_{AB} = -1$	0,25
$C_{BO} = \int_{BO} \vec{F} \cdot d\vec{OM} \text{ with } r = 1 \rightarrow 0, \phi = \text{undefined (not a problem since only } \vec{e}_r \text{ remains), } \theta = 0 \text{ and } d\vec{OM} = dr\vec{e}_r$	0,5
$C_{AB} = -\pi/4$	0,25
$C_{OC} = \int_{OC} \vec{F} \cdot d\vec{OM} \text{ with } r = 0 \rightarrow 1, \phi = 0, \theta = \pi/2 \text{ and } d\vec{OM} = dr\vec{e}_r$	0,5
$C_{AB} = \pi/2$	0,25
$C_{CA} = \int_{CA} \vec{F} \cdot d\vec{OM} \text{ with } r = 1, \phi = \pi/2 \rightarrow 0, \theta = \pi/2 \text{ and } d\vec{OM} = r \sin\theta d\phi\vec{e}_\phi = d\phi\vec{e}_\phi$	0,25
$C_{AB} = -\pi^3/16$	0,25
$\text{finally } C_{ABCOA} = \frac{-\pi^3 + 4\pi - 16}{16}$	0,25