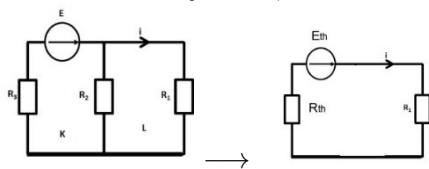
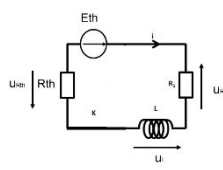
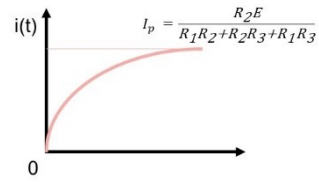
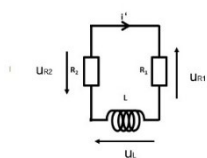
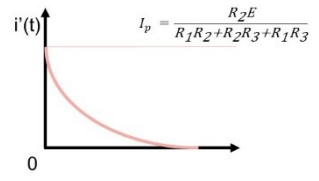


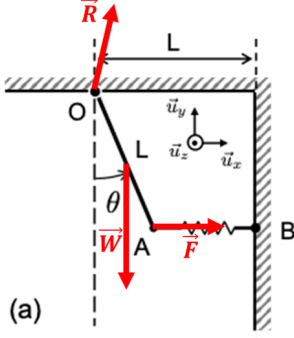
**Correction of the SCAN 1<sup>st</sup> Physics exam – Semester 1**  
**December 22<sup>nd</sup>, 2023**

**Exercise 1: Transient regime (10 points + 1 bonus)**

<p>1. In the steady state, the coil behaves like a closed switch</p>  <p><math>E_{th} = \frac{R_2 E}{R_2 + R_3}</math> and <math>R_{th} = \frac{R_2 R_3}{R_2 + R_3}</math> Hence <math>I_0 = \frac{E_{th}}{R_1 + R_{th}} = \frac{R_2 E}{R_1 R_2 + R_2 R_3 + R_1 R_3}</math></p>	<p>0.5 (equivalent dipole) 0.5 (circuit simplification) 0.5 (<math>I_0</math>)</p>
<p>2a. Scheme with the different quantities:</p>  <p>(KVL) <math>E_{th} = (R_1 + R_{th})i + L \frac{di}{dt}</math></p>	<p>1 (scheme) 0.5 (differential equation)</p>
<p>2b. Particular solution: <math>i_p(t) = \frac{E_{th}}{R_1 + R_{th}} = I_0</math> General solution of the complementary homogeneous equation: <math>i_h(t) = A e^{-\frac{t}{\tau}}</math> Initial condition: continuity of the current flowing through the coil <math>i(O^+) = i(O^-) = 0</math> gives <math>A = I_0</math> and <math>i(t) = I_0(1 - e^{-\frac{t}{\tau}})</math></p>	<p>0.5 (<math>i_p</math>) 0.5 (<math>i_h</math>) 0.5 (initial condition) 0.5 (<math>i(t)</math>)</p>
<p>2c.</p> 	<p>0.5 +0.5 if <math>\tau</math> shown on the scheme</p>
<p>2d. <math>i(t_\infty) = I_0</math> This is logical since <math>t_\infty</math> represents the steady state</p>	<p>+0.5</p>
<p>3a.</p>  <p>(KVL) <math>u_L = (R_1 + R_2)i'</math> with <math>u_L = -L \frac{di'}{dt}</math> thus <math>L \frac{di'}{dt} + (R_1 + R_2)i' = 0</math></p>	<p>0.5 (scheme) 0.5 (KVL) 0.5 (differential equation)</p>
<p>3b. general solution: <math>i'(t) = B e^{-\frac{t}{\tau}}</math> initial condition: <math>i'(O^+) = i'(O^-) = I</math> gives <math>B = I</math> and <math>i'(t) = I e^{-\frac{t}{\tau}}</math></p>	<p>0.5 (general solution) 0.5 (expression <math>i'</math>)</p>
<p>3c.</p> 	<p>0.25</p>
<p>3d. <math>W_{joule} = \int_0^\infty (R_1 + R_2)i'^2(t)dt = (R_1 + R_2)I^2 \int_0^\infty e^{-\frac{2t}{\tau}} dt = \frac{1}{2}LI^2</math></p>	<p>1.25</p>
<p>Energy stored in the coil at time <math>t = 0</math>: <math>W_0 = \frac{1}{2}LI^2</math> Energy stored in the coil at time <math>t_\infty</math>: <math>W_\infty = 0</math> The difference corresponds to the energy dissipated in the resistances, in agreement with question 3d</p>	<p>0.5</p>

## Exercise 2: Statics (~ 10 points)

### Part 1 - Study of the static equilibrium (6 points)

<p>1. system = rod OA Referential : Earth (assumed to be Galilean) List of external forces : weight <math>\vec{W}</math>, force <math>\vec{F}</math> exerted by the spring, reaction <math>\vec{R}</math> of the wall</p>  <p>(a)</p>	<p>1</p>
<p>2. <math>\vec{W} = -mg\vec{u}_y</math> <math>\vec{F} = +k(L(1 - \sin\theta) - \ell_0)\vec{u}_x</math> <math>\vec{R} = R_x\vec{u}_x + R_y\vec{u}_y</math> At equilibrium, <math>\mathcal{M}_O(\vec{W}) + \mathcal{M}_O(\vec{F}) + \mathcal{M}_O(\vec{R}) = \vec{0}</math> <math>\Leftrightarrow \vec{OG} \times \vec{W} + \vec{OA} \times \vec{F} + \vec{0} = \vec{0}</math> Hence <math>-\frac{1}{2}mg.\sin\theta + kL.\cos\theta.(L(1 - \sin\theta) - \ell_0) = 0</math> That is to say <math>mg.\tan\theta + 2kL.\sin\theta = 2k(L - \ell_0)</math></p>	<p>1 (forces) (0.5 if negative sign in the expression of <math>\vec{F}</math>) 0.5 (expression of the moments around point O) 1 (final result)</p>
<p>3. Small angle approximation : <math>\sin\theta \approx \tan\theta \approx \theta</math> therefore <math>mg.\theta_{eq} + 2kL\theta_{eq} \approx 2k(L - \ell_0)</math> <math>\theta_{eq} \approx \frac{2k(L - \ell_0)}{mg + 2kL}</math> Numerical application: <math>\theta_{eq} \approx 0.415 \text{ rad} \approx 23.8^\circ</math></p>	<p>1</p>
<p>4. <math>\theta_{eq} = 0</math> if <math>\ell_0 = L</math> or if <math>k = 0</math>. This is expected for a regular pendulum.</p>	<p>0.5</p>
<p>5. We use <math>\vec{W} + \vec{F} + \vec{R} = \vec{0}</math> we directly get <math>R_x = -k(L(1 - \sin(\theta)) - \ell_0)</math> ; <math>R_y = mg</math> and <math>R_z = 0</math></p>	<p>1</p>

### Part 2 - Rod crossed by a current $I$ immersed in a $\vec{B}$ field (4 points)

<p>1. Laplace force is exerted on the rod. It is equal to <math>\vec{F}_\ell = I.\vec{\ell} \times \vec{B}</math> By considering it applies at the middle of the rod, we obtain <math>\vec{F}_\ell = -I.B_0.L(\cos\theta.\vec{u}_x + \sin\theta.\vec{u}_y)</math></p>	<p>1</p>
<p>The new equilibrium is obtained for <math>\mathcal{M}_O(\vec{W}) + \mathcal{M}_O(\vec{F}) + \mathcal{M}_O(\vec{R}) + \mathcal{M}_O(\vec{F}_\ell) = \vec{0}</math> with <math>\mathcal{M}_O(\vec{F}_\ell) = -\frac{I.B_0.L^2}{2}.\vec{u}_z</math> Hence at equilibrium, <math>-mg.\sin\theta + kL.\cos\theta.(L(1 - \sin\theta) - \ell_0) - \frac{I.B_0.L^2}{2} = 0</math> We want <math>\theta = 0</math> thus <math>B_0 = \frac{2.k.(L - \ell_0)}{I.L}</math> Numerical application: <math>B_0 = 20 \text{ T}</math></p>	<p>2.5</p>
<p>3. <math>B_0 = 0</math> for <math>\ell_0 = L</math>. This is logical since we already have <math>\theta_{eq} = 0</math> (see Part 1 question 4)</p>	<p>0.5</p>