

Exercise 1.

1. The function \ln is continuous on $(0, 1]$, hence the integral I is improper at 0. Let $X \in (0, 1]$. Then:

$$I_X = \int_X^1 \ln(t) dt = [t \ln(t) - t]_{t=X}^{t=1} = -1 - X \ln(X) + X.$$

Now, $\lim_{X \rightarrow 0^+} X \ln(X) = 0$, hence $\lim_{X \rightarrow 0^+} I_X = -1 \in \mathbb{R}$, hence the improper integral I is convergent and $I = -1$.

2. The function $t \mapsto e^{-t} \ln(t)$ is continuous on $(0, +\infty)$. Hence the integral J is improper at 0 and at $+\infty$.

- *Convergence at 0:* since $e^{-t} \ln(t) \underset{t \rightarrow 0^*}{\sim} \ln(t) < 0$ and since, by Question 1, the improper integral

$$\int_0^1 \ln(t) dt$$

is convergent, we conclude that J is convergent at 0.

- *Convergence at $+\infty$:* we know that $\lim_{t \rightarrow +\infty} t^2 e^{-t} \ln(t) = 0$, hence there exists $A > 1$ such that

$$\forall t > A, 0 < t^2 e^{-t} \ln(t) < 1,$$

hence

$$\forall t > A, 0 < e^{-t} \ln(t) < \frac{1}{t^2}.$$

Since (by Riemann at $+\infty$ with $\alpha = 2 > 1$) the improper integral

$$\int_1^{\infty} \frac{dt}{t^2}$$

converges at $+\infty$, we conclude, by the comparison test, that J converges at $+\infty$.

Hence J is a convergent integral.

3. The function $t \mapsto e^{-t} \ln(t) \cos(t)$ is continuous on $(0, +\infty)$, hence the integral K is improper at $+\infty$.

- *Convergence at 0:* it is similar to the convergence at 0 of J : since $e^{-t} \ln(t) \cos(t) \underset{t \rightarrow 0^*}{\sim} \ln(t) < 0$, by the equivalent test, K converges at 0.
- *Convergence at $+\infty$:* observe that

$$\forall t > 1, 0 \leq |e^{-t} \ln(t) \cos(t)| \leq e^{-t} \ln(t)$$

and since, by Question 2 the improper integral

$$\int_1^{+\infty} e^{-t} \ln(t) dt$$

is convergent at $+\infty$ we conclude, by the Comparison Test, that K is absolutely convergent at $+\infty$, hence K is convergent at $+\infty$.

Hence K is a convergent integral.

Exercise 2.

1. Let $p \in \mathbb{R}$ and $\omega \in \mathbb{R}_+^*$. The functions $t \mapsto \cos(\omega t)e^{-pt}$ and $t \mapsto \sin(\omega t)e^{-pt}$ are continuous on $[0, +\infty)$, hence the integrals I and J are improper at $+\infty$.

Let $X > 0$ and define

$$I_X = \int_0^X \cos(\omega t)e^{-pt} dt \quad \text{and} \quad J_X = \int_0^X \sin(\omega t)e^{-pt} dt.$$

Then,

$$\begin{aligned}
 I_X + iJ_X &= \int_0^X (\cos(\omega t) + i \sin(\omega t)) e^{-pt} dt \\
 &= \int_0^X e^{i\omega t} e^{-pt} dt \quad \text{by Euler's Formula} \\
 &= \int_0^X e^{(-p+i\omega)t} dt \\
 &= \left[\frac{e^{(-p+i\omega)t}}{-p+i\omega} \right]_{t=0}^{t=X} \quad \text{since } -p+i\omega \neq 0 \\
 &= \frac{e^{(-p+i\omega)X} - 1}{-p+i\omega}.
 \end{aligned}$$

Now observe that since $p > 0$, one has $|e^{(-p+i\omega)X}| = e^{-pX} \xrightarrow{X \rightarrow +\infty} 0$ hence

$$\lim_{X \rightarrow +\infty} (I_X + iJ_X) = -\frac{1}{-p+i\omega} = \frac{p+i\omega}{p^2+\omega^2}.$$

Since I_X and J_X are real, we conclude that

$$\lim_{X \rightarrow +\infty} I_X = \frac{p}{p^2+\omega^2} \quad \text{and} \quad \lim_{X \rightarrow +\infty} J_X = \frac{\omega}{p^2+\omega^2},$$

hence I and J converge and

$$I = \frac{p}{p^2+\omega^2} \quad \text{and} \quad J = \frac{\omega}{p^2+\omega^2},$$

2. Let $\alpha \in \mathbb{R}$. The function $t \mapsto \frac{e^{-t}-1}{t^\alpha}$ is continuous on $(0, +\infty)$ hence the integral I_α is improper at 0 and at $+\infty$.

- *Convergence at 0*: we have the following equivalent:

$$\frac{e^{-t}-1}{t^\alpha} \underset{t \rightarrow 0^+}{\sim} \frac{-t}{t^\alpha} = -\frac{1}{t^{\alpha-1}} < 0,$$

and we know, by Riemann, that the improper integral

$$\int_0^1 \frac{dt}{t^{\alpha-1}}$$

converges (at 0) if and only if $\alpha - 1 < 1$ i.e., $\alpha < 2$. Hence, by the equivalent test, the improper integral I_α converges at 0 if and only if $\alpha < 2$.

- *Convergence at $+\infty$* : since $e^{-t}-1 \xrightarrow{t \rightarrow +\infty} -1$, we have the following equivalent:

$$\frac{e^{-t}-1}{t^\alpha} \underset{t \rightarrow +\infty}{\sim} -\frac{1}{t^\alpha} < 0,$$

and we know, by Riemann, that the improper integral

$$\int_1^{+\infty} \frac{dt}{t^\alpha}$$

converges (at $+\infty$) if and only if $\alpha > 1$. Hence, by the equivalent test, the improper integral I_α converges at $+\infty$ if and only if $\alpha > 1$.

Conclusion: the improper integral I_α converges if and only if $1 < \alpha < 2$.

Exercise 3.

1. Let φ be the linear mapping

$$\begin{aligned}
 \varphi : \mathbb{R}^2 &\longrightarrow \mathbb{R}^2 \\
 (x, y) &\longmapsto (2x - y, x - y).
 \end{aligned}$$

Then

$$[\varphi]_{\text{std}} = \begin{pmatrix} 2 & -1 \\ 1 & -1 \end{pmatrix},$$

and $\det \varphi = -1 \neq 0$ hence φ is invertible. It is clear that

$$\forall u \in \mathbb{R}^2, N(u) = \|\varphi(u)\|_1,$$

hence N is a norm on \mathbb{R}^2 .

2. Moreover, for $u \in \mathbb{R}^2$,

$$\begin{aligned} u \in B &\iff N(u) \leq 1 \\ &\iff \|\varphi(u)\|_1 \leq 1 \\ &\iff \varphi(u) \in B_{\|\cdot\|_1} \\ &\iff u \in \varphi^{-1}(B_{\|\cdot\|_1}) \end{aligned}$$

hence $B = \varphi^{-1}(B_{\|\cdot\|_1})$. Now,

$$[\varphi^{-1}]_{\text{std}} = \begin{pmatrix} 1 & -1 \\ 1 & -2 \end{pmatrix},$$

and we can understand graphically how B is obtained from $B_{\|\cdot\|_1}$: the ball $B_{\|\cdot\|_1}$ consists of the square with vertices $(0, 1)$, $(1, 0)$, $(-1, 0)$ and $(0, -1)$, hence the ball B consists of the parallelogram obtained by applying φ^{-1} to this square. To obtain it explicitly, we only need to determine the image of the two vertices $(0, 1)$ and $(1, 0)$ by φ , and use the fact that B is symmetric with respect to $(0, 0)$:

$$\varphi^{-1}((1, 0)) = (1, 1), \quad \varphi^{-1}((0, 1)) = (-1, -2).$$

We hence obtain the ball B shown on Figure 3.

Exercise 4.

1. Let $f_0 \in E$.

a) Let $h \in E$. Then

$$|\varphi(h)| = \left| \int_0^1 f_0(t)h(t) dt \right| \leq \int_0^1 |f_0(t)||h(t)| dt \leq \int_0^1 |f_0(t)|\|h\|_\infty dt = \|h\|_\infty \int_0^1 |f_0(t)| dt = \|h\|_\infty \|f_0\|_1.$$

Moreover,

$$\|f_0\|_1 = \int_0^1 |f_0(t)| dt \leq \int_0^1 \|f_0\|_\infty dt = \|f_0\|_\infty,$$

hence $\|f_0\|_1 \|h\|_\infty \leq \|f_0\|_\infty \|h\|_\infty$.

b) We notice that φ is a linear mapping, hence φ is continuous if and only if φ is continuous at 0_E . Now, from the previous inequality and the Squeeze Theorem, we conclude that:

$$\lim_{\|h\|_\infty \rightarrow 0} |\varphi(h)| = 0.$$

2. Let $f_0 \in E$ and let's show that Ψ is differentiable at f_0 and determine $d_{f_0}\Psi$: let $h \in E$. Then:

$$\Psi(f_0+h) = \int_0^1 (f_0(t)+h(t))^2 dt = \int_0^1 (f_0(t)^2 + 2f_0(t)h(t) + h(t)^2) dt = \int_0^1 f_0(t)^2 dt + 2 \int_0^1 f_0(t)h(t) dt + \int_0^1 h(t)^2 dt = \Psi(f_0)$$

where φ is the linear mapping of the previous question. Now we know (we already showed it in the previous question) that: $\|h^2\|_1 \leq \|h^2\|_\infty$, and $\|h^2\|_\infty = \|h\|_\infty^2$. Hence

$$\frac{\|h^2\|_1}{\|h\|_\infty} \leq \|h\|_\infty \xrightarrow{\|h\|_\infty \rightarrow 0} 0.$$

Since φ is linear and continuous, we conclude that Ψ is differentiable at f_0 and that

$$\begin{aligned} d_{f_0}\Psi : E &\longrightarrow \mathbb{R} \\ h &\longmapsto 2 \int_0^1 f_0(t)h(t) dt. \end{aligned}$$

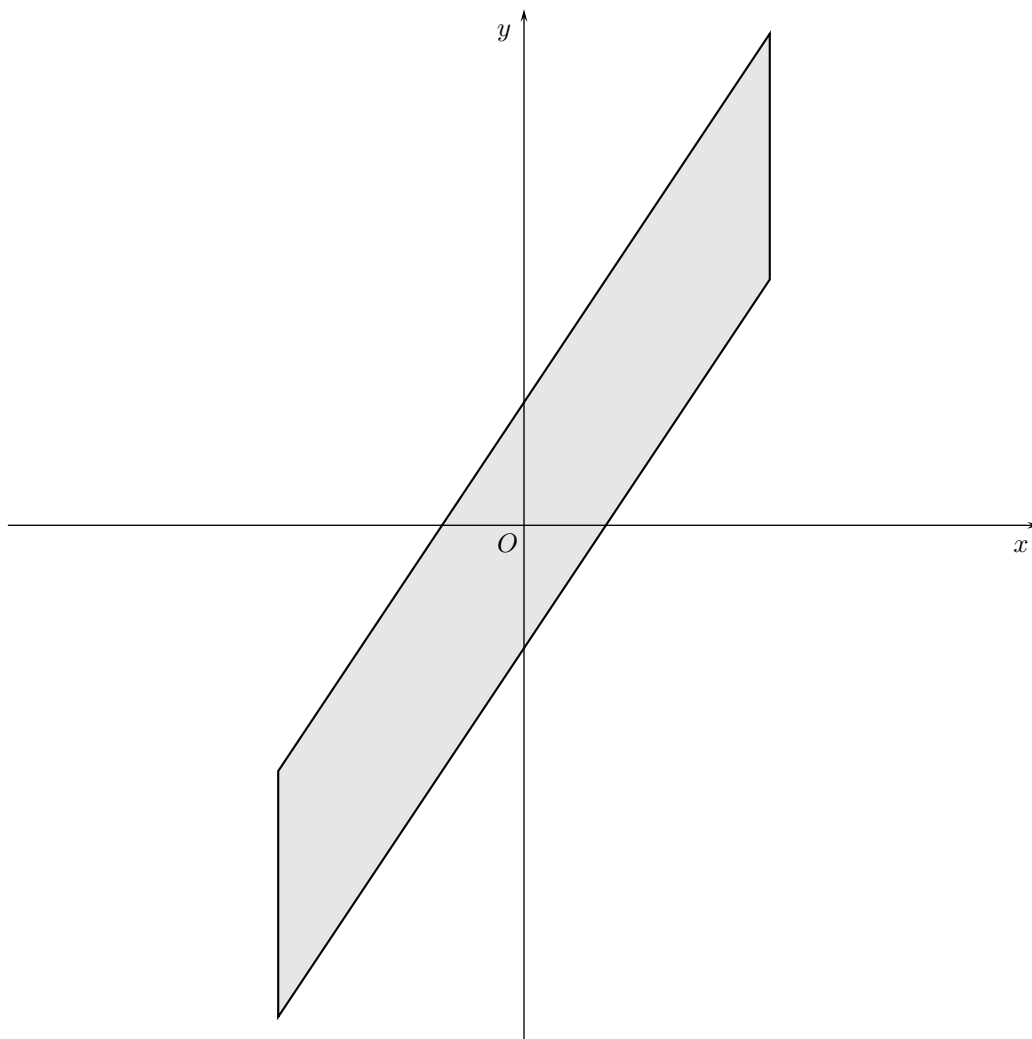


Figure 1. Ball B of Exercise 3

Exercise 5. Let $(x, y) \in \mathbb{R}^2 \setminus \{(0, 0)\}$. Then

$$|f(x, y)| = \frac{|xy|^{3/2}}{x^2 + 2y^2} \leq \frac{|xy|^{3/2}}{x^2 + y^2} \leq \frac{(\|(x, y)\|_2 \|(x, y)\|_2)^{3/2}}{\|(x, y)\|_2^2} = \|(x, y)\|_2 \xrightarrow{\|(x, y)\|_2 \rightarrow 0} 0.$$

Hence $\lim_{(x, y) \rightarrow (0, 0)} f(x, y) = 0$.

Exercise 6.

1.
 - Let $u \in E$ such that $N(u) = 0$. Then we must have, e.g., $N_2(u) = 0$ and hence, since N_2 is a norm on E we must have $u = 0_E$.
 - Let $u, v \in E$. Then since N_1 and N_2 are norms on E we have

$$N_1(u + v) \leq N_1(u) + N_1(v) \quad \text{and} \quad N_2(u + v) \leq N_2(u) + N_2(v)$$

Hence, by the Property (*) we also have $N(u+v) \leq \max\{N_1(u)+N_1(v), N_2(u)+N_2(v)\} \leq \max\{N_1(u), N_2(u)\} + \max\{N_1(v), N_2(v)\}$.

- Let $u \in E$ and $\lambda \in \mathbb{R}$. Then since N_1 and N_2 are norms on E we have

$$N_1(\lambda u) = |\lambda|N_1(u) \quad \text{and} \quad N_2(\lambda u) = |\lambda|N_2(u).$$

Hence $\max\{N_1(\lambda u), N_2(\lambda u)\} = \max\{|\lambda|N_1(u), |\lambda|N_2(u)\} = |\lambda| \max\{N_1(u), N_2(u)\} = |\lambda|N(u)$.

2. Let $u \in E$. Then

$$\begin{aligned}u \in B &\iff N(u) \leq 1 \\&\iff \max\{N_1(u), N_2(u)\} \leq 1 \\&\iff N_1(u) \leq 1 \text{ and } N_2(u) \leq 1 \\&\iff u \in B_1 \text{ and } u \in B_2 \\&\iff u \in B_1 \cap B_2.\end{aligned}$$

Hence $B = B_1 \cap B_2$.

3. a) The ball B is the intersection of two squares, as shown on Figure 2.

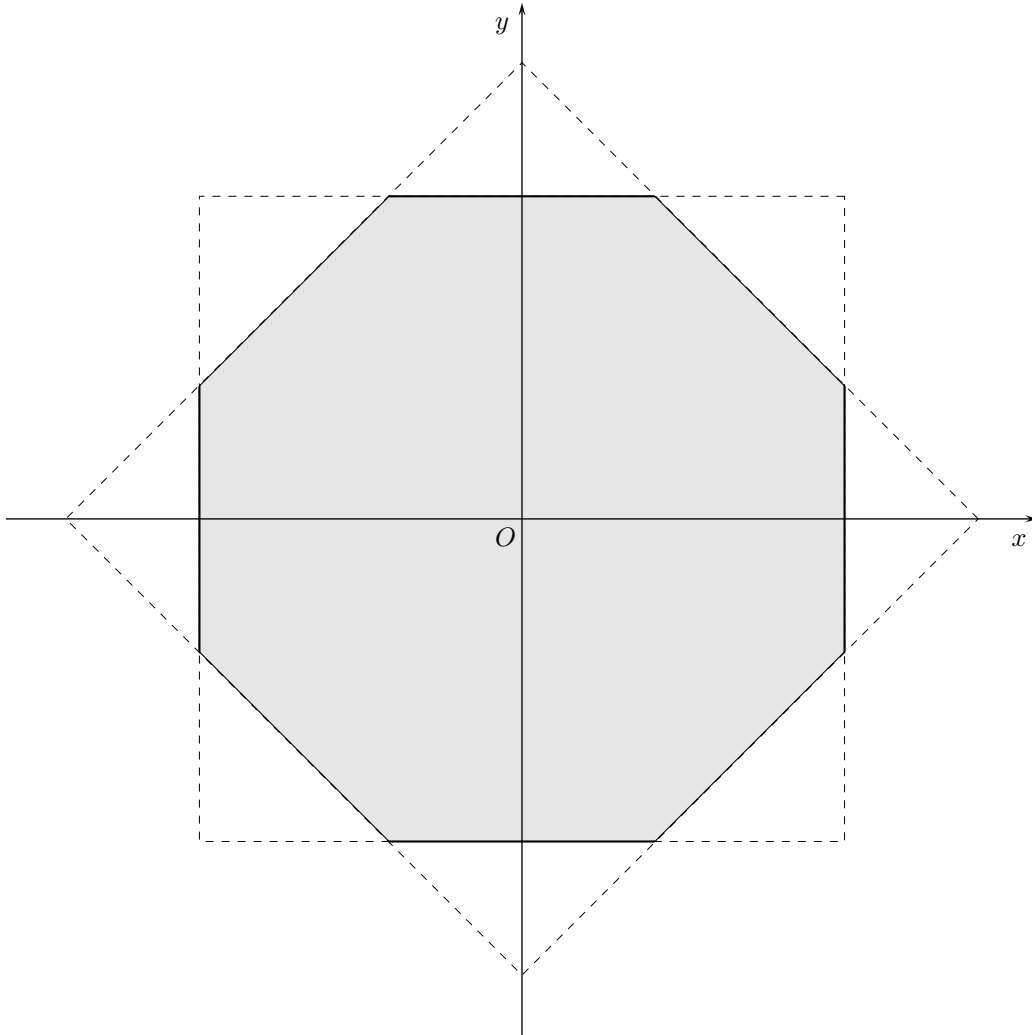


Figure 2. Ball B of Question 3a of Exercise 6

- b) i) The ball B is the intersection of the ellipse and the parallelogram, as shown on Figure 3(b)i.
ii) The set B_P is the union of the ellipse and the parallelogram, as shown on Figure 3(b)ii. We notice on the figure that this set is not convex, hence P cannot be a norm on \mathbb{R}^2 .
Hence, in general, P is not a norm on E .

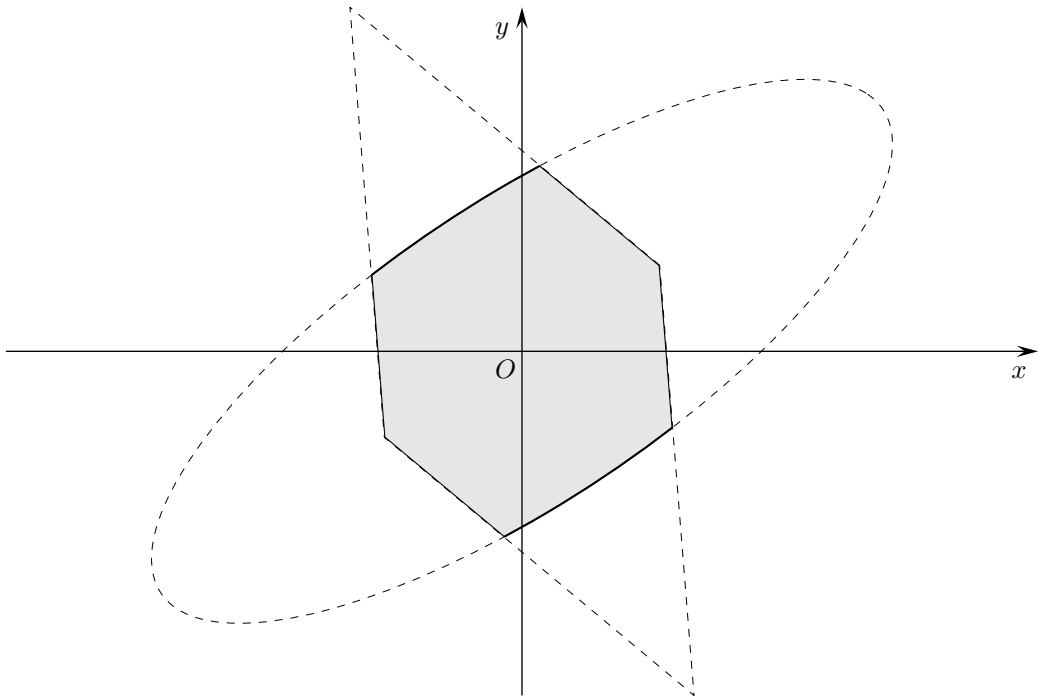


Figure 3. The ball B of Question 3(b)i of Exercise 6

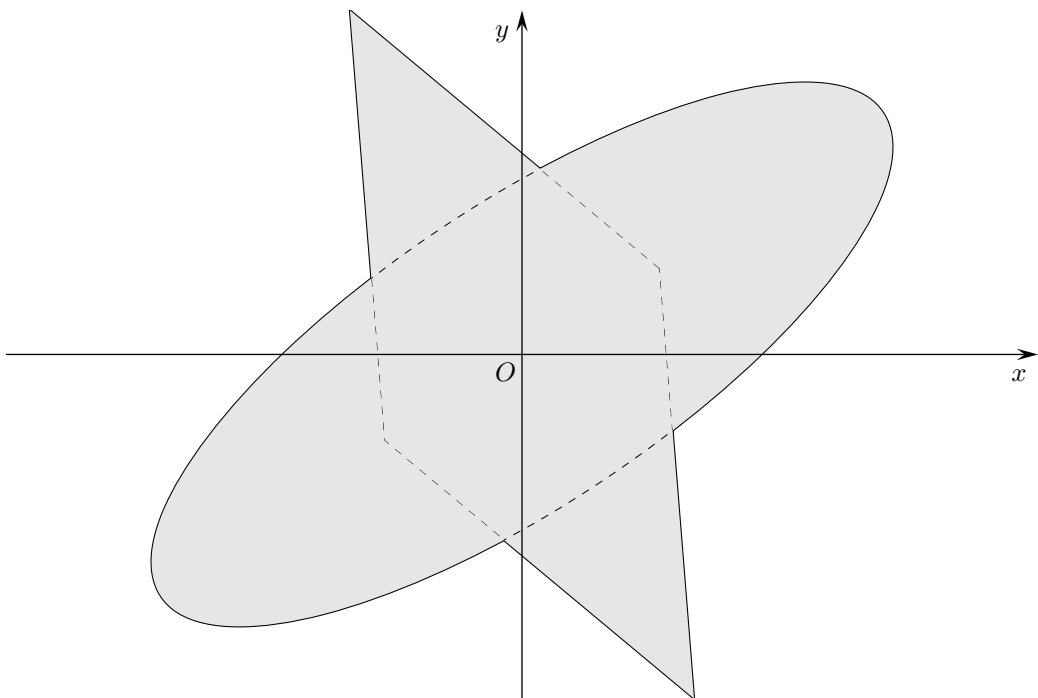


Figure 4. The set B_P of Question 3(b)ii of Exercise 6