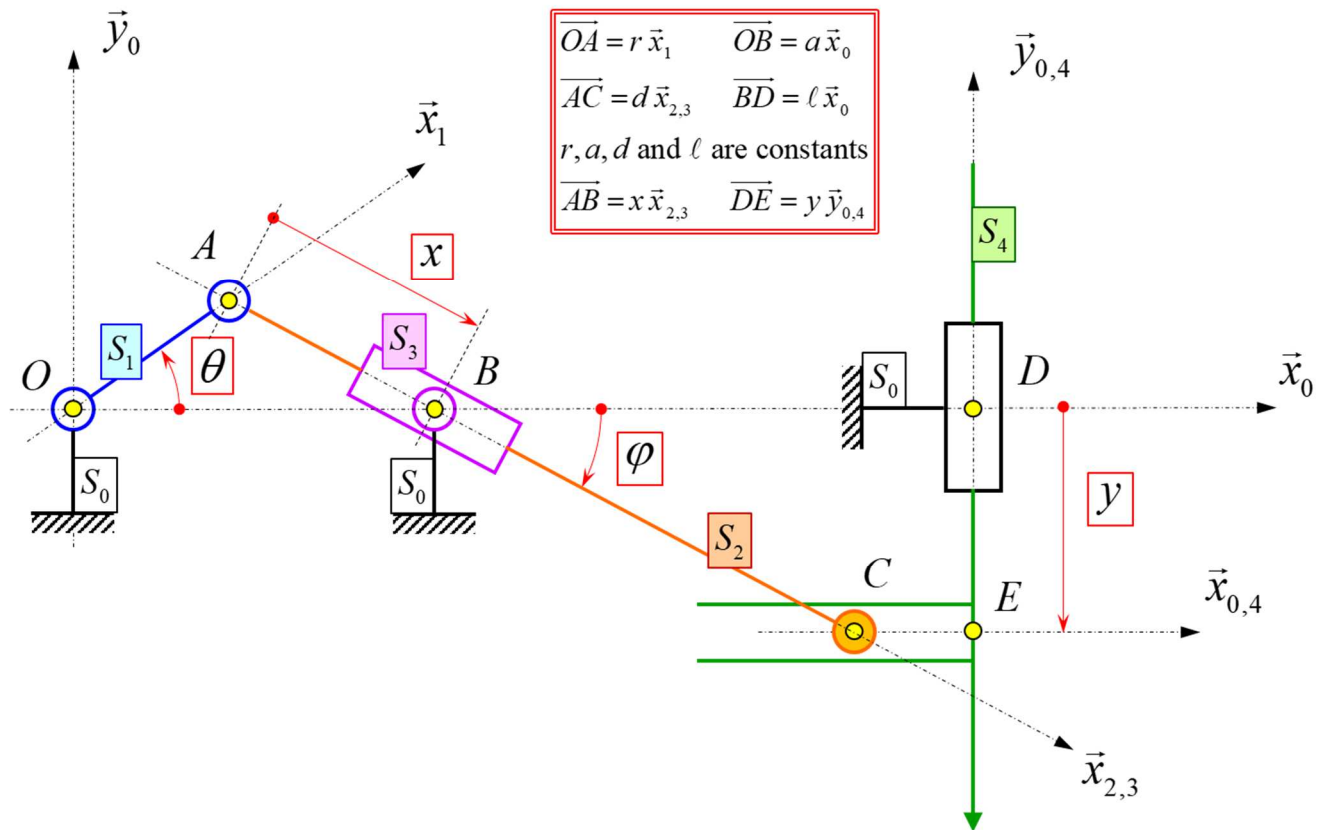


Kinematics

Please copy the following sentence: 'I hereby certify that I will not cheat and have no exchange of information with anybody but the teacher invigilating the test' and **sign** on your paper

The **planar system** shown in the figure below is used to operate a needle (S4) via a motion transformer known as Hoeckens mechanism. The principle of operation can be visualized with the animation "Hoeckens_linkage_Animated.gif".



The mechanism comprises :

- A crankshaft S1, connected to the ground S0 by a revolute joint of axis (O, \vec{z}) .

$$\text{Motion parameter for } 1/0 : \quad \theta = (\vec{x}_0, \vec{x}_1)$$

- A rod S2, connected to crankshaft S1 by a revolute joint of axis (A, \vec{z})

$$\text{Motion parameter for } 2/0 : \quad \varphi = (\vec{x}_0, \vec{x}_2)$$

- A rocker S3, connected to rod S2 by a prismatic joint of axis $(B, \vec{x}_{2,3})$

$$\text{Motion parameter for } 3/2 : \quad x = \overline{AB} \cdot \vec{x}_{2,3}$$

- Needle S4, connected to the ground S0 by a prismatic joint of axis $(D, \vec{y}_{0,4})$

$$\text{Motion parameter for } 4/0 : \quad y = \overline{DC} \cdot \vec{y}_0$$

Moreover :

- Rocker S3 is connected to the ground S0 by a revolute joint of axis (B, \vec{z}) **with no parameter.**
- Needle S4 is connected to rod S2 by a linear annular joint of axis $(E, \vec{x}_{0,4})$ **with no parameter.**

Questions :

- Q1** Graph of links and change of basis diagrams. (2)
- Q2** Develop the constraint equation(s) associated with the closure at point B. (3)
- Q3** Deduce the expressions of x and φ in terms of θ and the geometrical parameters a and r . (2)
- Q4** Calculate the velocity and acceleration of point A with respect to the ground S_0 . (2.5)
- Q4** Specify the nature of the motion $3/2$ and give the sum and moment about B of its kinematic screw (wrench) in terms of θ , $\dot{\theta}$, a and r . (3)
- Q5** Express the coordinates of \vec{BC} in terms of d and x . Deduce the velocity vector of point C with respect to the ground S_0 in terms of d, x, \dot{x} and $\dot{\varphi}$ (2.5)
- Q6** Give the condition imposed by the closure at point C. Deduce the expression of y in terms of d, x and φ (3)
- Q7** Determine the degree of mobility of the mechanism. (1)

Important:

Please note that:

- a) **1 mark** will be attributed to the quality of written expression, the respect of appropriate symbols and methodologies
- b) The absence of the ‘no-cheating’ statement and signature will be understood as a refusal to comply with the no-cheating policy and a mark of 0/20 will therefore be systematically assigned to this test.**